

ROL

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Contents

| | | |
|----------|--|-----------|
| 1 | ROL Documentation (Development Version) | 1 |
| 1.1 | Introduction | 1 |
| 1.2 | Overview | 1 |
| 1.3 | Quick Start | 2 |
| 1.3.1 | Step 1: Implement linear algebra / vector interface. | 2 |
| 1.3.2 | Step 2: Implement objective function interface. | 2 |
| 1.3.3 | Step 3: Choose optimization step. | 2 |
| 1.3.4 | Step 4: Set status test. | 2 |
| 1.3.5 | Step 5: Define an algorithm. | 2 |
| 1.3.6 | Step 6: Run algorithm. | 2 |
| 1.3.7 | Done! | 3 |
| 1.4 | Development Plans | 3 |
| 2 | Class Index | 5 |
| 2.1 | Class Hierarchy | 5 |
| 3 | Class Index | 7 |
| 3.1 | Class List | 7 |
| 4 | File Index | 9 |
| 4.1 | File List | 9 |
| 5 | Class Documentation | 11 |
| 5.1 | ROL::Algorithm Class Reference | 11 |

| | | |
|--------|--|----|
| 5.1.1 | Detailed Description | 11 |
| 5.2 | ROL::AlgorithmState< Real > Struct Template Reference | 12 |
| 5.2.1 | Detailed Description | 12 |
| 5.3 | ROL::BarzilaiBorwein< Real > Class Template Reference | 13 |
| 5.3.1 | Detailed Description | 13 |
| 5.4 | ROL::DefaultAlgorithm< Real > Class Template Reference | 14 |
| 5.4.1 | Detailed Description | 14 |
| 5.5 | ROL::EpetraMultiVector< Real > Class Template Reference | 15 |
| 5.5.1 | Detailed Description | 16 |
| 5.6 | ROL::Krylov< Real > Class Template Reference | 17 |
| 5.6.1 | Detailed Description | 17 |
| 5.7 | ROL::IBFGS< Real > Class Template Reference | 18 |
| 5.7.1 | Detailed Description | 18 |
| 5.8 | ROL::IDFP< Real > Class Template Reference | 19 |
| 5.8.1 | Detailed Description | 19 |
| 5.9 | ROL::LineSearch< Real > Class Template Reference | 20 |
| 5.9.1 | Detailed Description | 21 |
| 5.10 | ROL::LineSearchStep< Real > Class Template Reference | 22 |
| 5.10.1 | Detailed Description | 23 |
| 5.11 | ROL::ISR1< Real > Class Template Reference | 24 |
| 5.11.1 | Detailed Description | 24 |
| 5.12 | ROL::NonlinearCG< Real > Class Template Reference | 25 |
| 5.12.1 | Detailed Description | 25 |
| 5.13 | ROL::NonlinearCGState< Real > Struct Template Reference | 26 |
| 5.13.1 | Detailed Description | 26 |
| 5.14 | ROL::Objective< Real > Class Template Reference | 27 |
| 5.14.1 | Detailed Description | 28 |
| 5.15 | ROL::Objective_Beale< Real > Class Template Reference | 29 |
| 5.15.1 | Detailed Description | 29 |
| 5.16 | ROL::Objective_FreudensteinRoth< Real > Class Template Reference | 31 |
| 5.16.1 | Detailed Description | 31 |

| | | |
|--------|--|----|
| 5.17 | ROL::Objective_LeastSquares< Real > Class Template Reference . . . | 32 |
| 5.17.1 | Detailed Description | 32 |
| 5.18 | ROL::Objective_PoissonControl< Real > Class Template Reference . | 33 |
| 5.18.1 | Detailed Description | 33 |
| 5.19 | ROL::Objective_PoissonInversion< Real > Class Template Reference | 35 |
| 5.19.1 | Detailed Description | 36 |
| 5.20 | ROL::Objective_Powell< Real > Class Template Reference | 37 |
| 5.20.1 | Detailed Description | 37 |
| 5.21 | ROL::Objective_Rosenbrock< Real > Class Template Reference . . . | 38 |
| 5.21.1 | Detailed Description | 38 |
| 5.22 | ROL::Objective_SumOfSquares< Real > Class Template Reference . | 40 |
| 5.22.1 | Detailed Description | 40 |
| 5.23 | ROL::Secant< Real > Class Template Reference | 41 |
| 5.23.1 | Detailed Description | 41 |
| 5.24 | ROL::SecantState< Real > Struct Template Reference | 42 |
| 5.24.1 | Detailed Description | 42 |
| 5.25 | ROL::StatusTest< Real > Class Template Reference | 43 |
| 5.25.1 | Detailed Description | 43 |
| 5.26 | ROL::StdVector< Real, Element > Class Template Reference | 44 |
| 5.26.1 | Detailed Description | 45 |
| 5.27 | ROL::Step< Real > Class Template Reference | 46 |
| 5.27.1 | Detailed Description | 47 |
| 5.28 | ROL::StepState< Real > Struct Template Reference | 48 |
| 5.28.1 | Detailed Description | 48 |
| 5.29 | ROL::TrustRegion< Real > Class Template Reference | 49 |
| 5.29.1 | Detailed Description | 50 |
| 5.30 | ROL::TrustRegionStep< Real > Class Template Reference | 51 |
| 5.30.1 | Detailed Description | 52 |
| 5.31 | ROL::Vector< Real > Class Template Reference | 53 |
| 5.31.1 | Detailed Description | 54 |

| | | |
|----------|---|-----------|
| 6 | File Documentation | 55 |
| 6.1 | example_01.cpp File Reference | 55 |
| 6.1.1 | Detailed Description | 56 |
| 6.2 | ROL_Beale.hpp File Reference | 57 |
| 6.2.1 | Detailed Description | 57 |
| 6.3 | ROL_FreudensteinRoth.hpp File Reference | 58 |
| 6.3.1 | Detailed Description | 58 |
| 6.4 | ROL_LeastSquares.hpp File Reference | 59 |
| 6.4.1 | Detailed Description | 59 |
| 6.5 | ROL_PoissonControl.hpp File Reference | 60 |
| 6.5.1 | Detailed Description | 60 |
| 6.6 | ROL_PoissonInversion.hpp File Reference | 61 |
| 6.6.1 | Detailed Description | 61 |
| 6.7 | ROL_Powell.hpp File Reference | 62 |
| 6.7.1 | Detailed Description | 62 |
| 6.8 | ROL_Rosenbrock.hpp File Reference | 63 |
| 6.8.1 | Detailed Description | 63 |
| 6.9 | ROL_SumOfSquares.hpp File Reference | 64 |
| 6.9.1 | Detailed Description | 64 |
| 6.10 | ROL_TestObjectives.hpp File Reference | 65 |
| 6.10.1 | Detailed Description | 65 |
| 6.11 | ROL_Types.hpp File Reference | 66 |
| 6.11.1 | Detailed Description | 69 |

Chapter 1

ROL Documentation (Development Version)

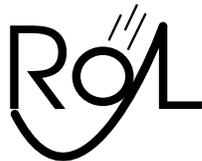


Figure 1.1: Rapid Optimization Library

1.1 Introduction

ROL, the Rapid Optimization Library, is a Trilinos package for matrix-free optimization.

1.2 Overview

Current release of ROL includes the following features:

- Unconstrained optimization algorithms.

1.3 Quick Start

The Rosenbrock example (rol/example/rosenbrock/example_01.cpp) demonstrates the use of ROL. It amounts to six steps:

1.3.1 Step 1: Implement linear algebra / vector interface.

--- or try one of the provided implementations, such as `ROL::StdVector` in `rol/vector`.

```
ROL::Vector
```

1.3.2 Step 2: Implement objective function interface.

--- or try one of the provided functions, such as `ROL::Objective_Rosenbrock` in `rol/zoo`.

```
ROL::Objective
```

1.3.3 Step 3: Choose optimization step.

--- with `ParameterList` settings in the variable `parlist`.

```
ROL::LineSearchStep<RealT> step(parlist);
```

1.3.4 Step 4: Set status test.

--- with gradient tolerance `{gtol}`, step tolerance `{stol}` and the maximum number of iterations `{maxit}`.

```
ROL::StatusTest<RealT> status(gtol, stol, maxit);
```

1.3.5 Step 5: Define an algorithm.

--- based on the status test and the step.

```
ROL::DefaultAlgorithm<RealT> algo(step, status);
```

1.3.6 Step 6: Run algorithm.

--- starting from the initial iterate `{x}`, applied to objective function `{obj}`.

```
algo.run(x, obj);
```

1.3.7 Done!

1.4 Development Plans

Constrained optimization, optimization under uncertainty, etc.

Chapter 2

Class Index

2.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

| | |
|---|----|
| ROL::Algorithm | 11 |
| ROL::AlgorithmState< Real > | 12 |
| ROL::DefaultAlgorithm< Real > | 14 |
| ROL::Krylov< Real > | 17 |
| ROL::LineSearch< Real > | 20 |
| ROL::NonlinearCG< Real > | 25 |
| ROL::NonlinearCGState< Real > | 26 |
| ROL::Objective< Real > | 27 |
| ROL::Objective_Beale< Real > | 29 |
| ROL::Objective_FreudensteinRoth< Real > | 31 |
| ROL::Objective_LeastSquares< Real > | 32 |
| ROL::Objective_PoissonControl< Real > | 33 |
| ROL::Objective_PoissonInversion< Real > | 35 |
| ROL::Objective_Powell< Real > | 37 |
| ROL::Objective_Rosenbrock< Real > | 38 |
| ROL::Objective_SumOfSquares< Real > | 40 |
| ROL::Secant< Real > | 41 |
| ROL::BarzilaiBorwein< Real > | 13 |
| ROL::IBFGS< Real > | 18 |
| ROL::IDFP< Real > | 19 |
| ROL::ISR1< Real > | 24 |
| ROL::SecantState< Real > | 42 |
| ROL::StatusTest< Real > | 43 |
| ROL::Step< Real > | 46 |
| ROL::LineSearchStep< Real > | 22 |

| | |
|---|----|
| ROL::TrustRegionStep< Real > | 51 |
| ROL::StepState< Real > | 48 |
| ROL::TrustRegion< Real > | 49 |
| ROL::Vector< Real > | 53 |
| ROL::EpetraMultiVector< Real > | 15 |
| ROL::StdVector< Real, Element > | 44 |

Chapter 3

Class Index

3.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

| | |
|---|----|
| ROL::Algorithm (Provides an interface to run optimization algorithms) | 11 |
| ROL::AlgorithmState< Real > | 12 |
| ROL::BarzilaiBorwein< Real > (Provides definitions for Barzilai-Borwein operators) | 13 |
| ROL::DefaultAlgorithm< Real > | 14 |
| ROL::EpetraMultiVector< Real > (Implements the ROL::Vector interface for an <code>Epetra_MultiVector</code>) | 15 |
| ROL::Krylov< Real > (Provides definitions for Krylov solvers) | 17 |
| ROL::LBFGS< Real > (Provides definitions for limited-memory BFGS operators) | 18 |
| ROL::IDFP< Real > (Provides definitions for limited-memory DFP operators) | 19 |
| ROL::LineSearch< Real > (Provides interface for and implements line searches) | 20 |
| ROL::LineSearchStep< Real > (Provides the interface to compute optimization steps with line search) | 22 |
| ROL::LSR1< Real > (Provides definitions for limited-memory SR1 operators) | 24 |
| ROL::NonlinearCG< Real > (Implementats nonlinear conjugate gradient methods) | 25 |
| ROL::NonlinearCGState< Real > | 26 |
| ROL::Objective< Real > (Provides the interface to evaluate objective functions) | 27 |
| ROL::Objective_Beale< Real > (Beale's function) | 29 |

| | |
|--|----|
| ROL::Objective_FreudensteinRoth< Real > (Freudenstein and Roth's function) | 31 |
| ROL::Objective_LeastSquares< Real > (Least squares function) | 32 |
| ROL::Objective_PoissonControl< Real > (Poisson distributed control) | 33 |
| ROL::Objective_PoissonInversion< Real > (Poisson material inversion) | 35 |
| ROL::Objective_Powell< Real > (Powell's badly scaled function) | 37 |
| ROL::Objective_Rosenbrock< Real > (Rosenbrock's function) | 38 |
| ROL::Objective_SumOfSquares< Real > (Sum of squares function) | 40 |
| ROL::Secant< Real > (Provides interface for and implements limited-memory secant operators) | 41 |
| ROL::SecantState< Real > | 42 |
| ROL::StatusTest< Real > (Provides an interface to check status of optimization algorithms) | 43 |
| ROL::StdVector< Real, Element > (Provides the std::vector implementation of the ROL::Vector interface) | 44 |
| ROL::Step< Real > (Provides the interface to compute optimization steps) | 46 |
| ROL::StepState< Real > | 48 |
| ROL::TrustRegion< Real > (Provides interface for and implements trust-region subproblem solvers) | 49 |
| ROL::TrustRegionStep< Real > (Provides the interface to compute optimization steps with trust regions) | 51 |
| ROL::Vector< Real > (Provides the vector space interface) | 53 |

Chapter 4

File Index

4.1 File List

Here is a list of all documented files with brief descriptions:

| | |
|---|----|
| example_01.cpp (Shows how to minimize Rosenbrock's function using Newton-Krylov) | 55 |
| ROL_Algorithm.hpp | ?? |
| ROL_BarzilaiBorwein.hpp | ?? |
| ROL_Beale.hpp (Contains definitions for Beale's function) | 57 |
| ROL_EpetraMultiVector.hpp | ?? |
| ROL_FreudensteinRoth.hpp (Contains definitions for Freudenstein and Roth's function) | 58 |
| ROL_Krylov.hpp | ?? |
| ROL_IBFGS.hpp | ?? |
| ROL_IDFP.hpp | ?? |
| ROL_LeastSquares.hpp (Contains definitions for least squares function) | 59 |
| ROL_LineSearch.hpp | ?? |
| ROL_LineSearchStep.hpp | ?? |
| ROL_ISR1.hpp | ?? |
| ROL_NonlinearCG.hpp | ?? |
| ROL_Objective.hpp | ?? |
| ROL_ObjectiveDef.hpp | ?? |
| ROL_PoissonControl.hpp (Contains definitions for Poisson optimal control) | 60 |
| ROL_PoissonInversion.hpp (Contains definitions for Poisson material inversion) | 61 |
| ROL_Powell.hpp (Contains definitions for Powell's badly scaled function) | 62 |
| ROL_Rosenbrock.hpp (Contains definitions for Rosenbrock's function) | 63 |
| ROL_Secant.hpp | ?? |
| ROL_StatusTest.hpp | ?? |

| | |
|---|----|
| ROL_StdVector.hpp | ?? |
| ROL_Step.hpp | ?? |
| ROL_SumOfSquares.hpp (Contains definitions for sum of squares function) | 64 |
| ROL_TestObjectives.hpp (Contains definitions of test objective functions) | 65 |
| ROL_TrustRegion.hpp | ?? |
| ROL_TrustRegionStep.hpp | ?? |
| ROL_Types.hpp (Contains definitions of custom data types in ROL) | 66 |
| ROL_Vector.hpp | ?? |
| function/test_01.cpp | ?? |
| step/test_01.cpp | ?? |
| vector/test_01.cpp | ?? |
| step/test_02.cpp | ?? |
| vector/test_02.cpp | ?? |

Chapter 5

Class Documentation

5.1 ROL::Algorithm Class Reference

Provides an interface to run optimization algorithms.

```
#include <ROL_Algorithm.hpp>
```

5.1.1 Detailed Description

Provides an interface to run optimization algorithms.

The documentation for this class was generated from the following file:

- ROL_Algorithm.hpp

5.2 ROL::AlgorithmState< Real > Struct Template Reference

Public Attributes

- int **iter**
- int **nfval**
- int **ngrad**
- Real **value**
- Real **gnorm**
- Real **snorm**
- Teuchos::RCP< [Vector](#)< Real > > **iterateVec**

5.2.1 Detailed Description

`template<class Real> struct ROL::AlgorithmState< Real >`

Definition at line 58 of file ROL_Step.hpp.

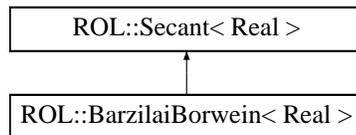
The documentation for this struct was generated from the following file:

- ROL_Step.hpp

5.3 ROL::BarzilaiBorwein< Real > Class Template Reference

Provides definitions for Barzilai-Borwein operators.

```
#include <ROL_BarzilaiBorwein.hpp>Inheritance diagram for ROL::BarzilaiBorwein< Real >::
```



Public Member Functions

- **BarzilaiBorwein** (int type=1)
- void **applyH** ([Vector](#)< Real > &Hv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &x)
- void **applyB** ([Vector](#)< Real > &Bv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &x)

Private Attributes

- int type_

5.3.1 Detailed Description

template<class Real> **class** ROL::BarzilaiBorwein< Real >

Provides definitions for Barzilai-Borwein operators.

Definition at line 54 of file ROL_BarzilaiBorwein.hpp.

The documentation for this class was generated from the following file:

- ROL_BarzilaiBorwein.hpp

5.4 ROL::DefaultAlgorithm< Real > Class Template Reference

Public Member Functions

- **DefaultAlgorithm** ([Step](#)< Real > &step, [StatusTest](#)< Real > &status, bool printHeader=false)
- virtual std::vector< std::string > **run** ([Vector](#)< Real > &x, [Objective](#)< Real > &obj, bool print=false)
Run algorithm.
- std::string **getIterHeader** (void)
- std::string **getIterInfo** (bool withHeader=false)

Private Attributes

- Teuchos::RCP< [Step](#)< Real > > **step_**
- Teuchos::RCP< [StatusTest](#)< Real > > **status_**
- Teuchos::RCP< [AlgorithmState](#)< Real > > **state_**
- bool **printHeader_**

5.4.1 Detailed Description

`template<class Real> class ROL::DefaultAlgorithm< Real >`

Definition at line 58 of file ROL_Algorithm.hpp.

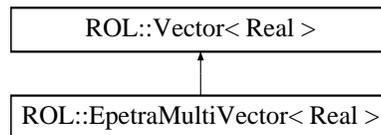
The documentation for this class was generated from the following file:

- ROL_Algorithm.hpp

5.5 ROL::EpetraMultiVector< Real > Class Template Reference

Implements the [ROL::Vector](#) interface for an Epetra_MultiVector.

`#include <ROL_EpetraMultiVector.hpp>` [Inheritance diagram](#) for ROL::EpetraMultiVector< Real >::



Public Member Functions

- **EpetraMultiVector** (const Teuchos::RCP< Epetra_MultiVector > &epetra_vec)
- void **plus** (const [Vector](#)< Real > &x)
*Compute $y \leftarrow x + y$ where $y = *this$.*
- void **scale** (const Real alpha)
*Compute $y \leftarrow \alpha y$ where $y = *this$.*
- Real **dot** (const [Vector](#)< Real > &x) const
*Returns $\langle y, x \rangle$ where $y = *this$.*
- Real **norm** () const
*Returns $\|y\|$ where $y = *this$.*
- Teuchos::RCP< [Vector](#)< Real > > **clone** () const
Clone to make a new (uninitialized) vector.
- virtual void **axpy** (const Real alpha, const [Vector](#)< Real > &x)
*Compute $y \leftarrow \alpha x + y$ where $y = *this$.*
- virtual void **zero** ()
Set to zero vector.
- virtual void **set** (const [Vector](#)< Real > &x)
*Set $y \leftarrow x$ where $y = *this$.*

- Teuchos::RCP< const Epetra_MultiVector > **getVector** () const
- Teuchos::RCP< Vector< Real > > **basis** (const int i) const
Return i-th basis vector: define if finite-difference gradients and Hessians are used.
- int **dimension** () const

Private Attributes

- Teuchos::RCP< Epetra_MultiVector > **epetra_vec_**

5.5.1 Detailed Description

template<class Real> class ROL::EpetraMultiVector< Real >

Implements the [ROL::Vector](#) interface for an Epetra_MultiVector.

Definition at line 61 of file ROL_EpetraMultiVector.hpp.

The documentation for this class was generated from the following file:

- ROL_EpetraMultiVector.hpp

5.6 ROL::Krylov< Real > Class Template Reference

Provides definitions for [Krylov](#) solvers.

```
#include <ROL_Krylov.hpp>
```

Public Member Functions

- **Krylov** (Real tol1=1.e-4, Real tol2=1.e-2, int maxit=100, bool useInexact=false)
- void **CG** ([Vector](#)< Real > &s, int &iter, int &flag, const [Vector](#)< Real > &g, const [Vector](#)< Real > &x, [Objective](#)< Real > &obj, Teuchos::RCP< [Secant](#)< Real > > secant=Teuchos::null)

Private Attributes

- Real **tol1_**
- Real **tol2_**
- int **maxit_**
- bool **useInexact_**

5.6.1 Detailed Description

`template<class Real> class ROL::Krylov< Real >`

Provides definitions for [Krylov](#) solvers.

Definition at line 54 of file ROL_Krylov.hpp.

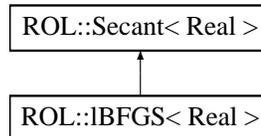
The documentation for this class was generated from the following file:

- ROL_Krylov.hpp

5.7 ROL::IBFGS< Real > Class Template Reference

Provides definitions for limited-memory BFGS operators.

`#include <ROL_IBFGS.hpp>`Inheritance diagram for ROL::IBFGS< Real >::



Public Member Functions

- **IBFGS** (int M)
- void **applyH** ([Vector](#)< Real > &Hv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &x)
- void **applyB** ([Vector](#)< Real > &Bv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &x)

5.7.1 Detailed Description

`template<class Real> class ROL::IBFGS< Real >`

Provides definitions for limited-memory BFGS operators.

Definition at line 54 of file ROL_IBFGS.hpp.

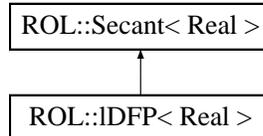
The documentation for this class was generated from the following file:

- ROL_IBFGS.hpp

5.8 ROL::IDFP< Real > Class Template Reference

Provides definitions for limited-memory DFP operators.

`#include <ROL_IDFP.hpp>` Inheritance diagram for ROL::IDFP< Real >::



Public Member Functions

- **IDFP** (int M)
- void **applyH** (Vector< Real > &Hv, const Vector< Real > &v, const Vector< Real > &x)
- virtual void **applyH0** (Vector< Real > &Hv, const Vector< Real > &v, const Vector< Real > &x)
- void **applyB** (Vector< Real > &Bv, const Vector< Real > &v, const Vector< Real > &x)
- virtual void **applyB0** (Vector< Real > &Bv, const Vector< Real > &v, const Vector< Real > &x)

5.8.1 Detailed Description

`template<class Real> class ROL::IDFP< Real >`

Provides definitions for limited-memory DFP operators.

Definition at line 54 of file ROL_IDFP.hpp.

The documentation for this class was generated from the following file:

- ROL_IDFP.hpp

5.9 ROL::LineSearch< Real > Class Template Reference

Provides interface for and implements line searches.

```
#include <ROL_LineSearch.hpp>
```

Public Member Functions

- **LineSearch** (Teuchos::ParameterList &parlist)
- bool **status** (const ELineSearch type, int &ls_neval, int &ls_ngrad, const Real alpha, const Real fold, const Real sgold, const Real fnew, const [Vector](#)< Real > &x, const [Vector](#)< Real > &s, [Objective](#)< Real > &obj)
- void **run** (Real &alpha, Real &fval, int &ls_neval, int &ls_ngrad, const Real &gs, const [Vector](#)< Real > &s, const [Vector](#)< Real > &x, [Objective](#)< Real > &obj)
- void **simplebacktracking** (Real &alpha, Real &fval, int &ls_neval, int &ls_ngrad, const Real &gs, const [Vector](#)< Real > &s, const [Vector](#)< Real > &x, [Objective](#)< Real > &obj)
- void **backtracking** (Real &alpha, Real &fval, int &ls_neval, int &ls_ngrad, const Real &gs, const [Vector](#)< Real > &s, const [Vector](#)< Real > &x, [Objective](#)< Real > &obj)
- void **bisection** (Real &alpha, Real &fval, int &ls_neval, int &ls_ngrad, const Real &gs, const [Vector](#)< Real > &s, const [Vector](#)< Real > &x, [Objective](#)< Real > &obj)
- void **goldensection** (Real &alpha, Real &fval, int &ls_neval, int &ls_ngrad, const Real &gs, const [Vector](#)< Real > &s, const [Vector](#)< Real > &x, [Objective](#)< Real > &obj)
- void **brents** (Real &alpha, Real &fval, int &ls_neval, int &ls_ngrad, const Real &gs, const [Vector](#)< Real > &s, const [Vector](#)< Real > &x, [Objective](#)< Real > &obj)

Private Attributes

- ELineSearch **els_**
- ECurvatureCondition **econd_**
- EDescent **edesc_**
- int **maxit_**
- Real **c1_**
- Real **c2_**
- Real **tol_**
- Real **rho_**
- Real **alpha0_**
- bool **useralpha_**

5.9.1 Detailed Description

template<class Real> class ROL::LineSearch< Real >

Provides interface for and implements line searches.

Definition at line 54 of file ROL_LineSearch.hpp.

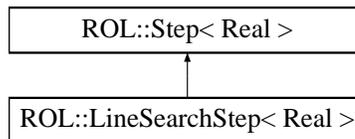
The documentation for this class was generated from the following file:

- ROL_LineSearch.hpp

5.10 ROL::LineSearchStep< Real > Class Template Reference

Provides the interface to compute optimization steps with line search.

`#include <ROL_LineSearchStep.hpp>` Inheritance diagram for ROL::LineSearchStep< Real >::



Public Member Functions

- **LineSearchStep** (Teuchos::ParameterList &parlist)
- **LineSearchStep** (Teuchos::RCP< [Secant](#)< Real > > &secant, Teuchos::ParameterList &parlist)
- void **compute** (Vector< Real > &s, const Vector< Real > &x, [Objective](#)< Real > &obj, [AlgorithmState](#)< Real > &algo_state)

Compute step.
- void **update** (Vector< Real > &x, const Vector< Real > &s, [Objective](#)< Real > &obj, [AlgorithmState](#)< Real > &algo_state)

Update step, if successful.
- std::string **printHeader** (void) const

Print iterate header.
- std::string **printName** (void) const

Print step name.
- std::string **print** ([AlgorithmState](#)< Real > &algo_state, bool printHeader=false) const

Print iterate status.

Private Attributes

- Teuchos::RCP< [Secant](#)< Real > > **secant_**
- Teuchos::RCP< [Krylov](#)< Real > > **krylov_**

- Teuchos::RCP< [NonlinearCG](#)< Real > > **nlg_**
- Teuchos::RCP< [LineSearch](#)< Real > > **lineSearch_**
- int **iterKrylov_**
- int **flagKrylov_**
- ELineSearch **els_**
- ECurvatureCondition **econd_**
- EDescent **edesc_**
- ESecant **esec_**
- int **ls_nfval_**
- int **ls_ngrad_**
- std::vector< bool > **useInexact_**

5.10.1 Detailed Description

template<class Real> class ROL::LineSearchStep< Real >

Provides the interface to compute optimization steps with line search.

Definition at line 65 of file ROL_LineSearchStep.hpp.

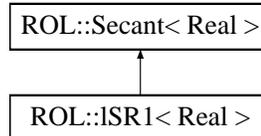
The documentation for this class was generated from the following file:

- ROL_LineSearchStep.hpp

5.11 ROL::ISR1< Real > Class Template Reference

Provides definitions for limited-memory SR1 operators.

`#include <ROL_ISR1.hpp>`Inheritance diagram for ROL::ISR1< Real >::



Public Member Functions

- **ISR1** (int M)
- void **update** (const [Vector](#)< Real > &grad, const [Vector](#)< Real > &gp, const [Vector](#)< Real > &s, const Real snorm, const int iter)
- virtual void **applyH0** ([Vector](#)< Real > &Hv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &x)
- void **applyH** ([Vector](#)< Real > &Hv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &x)
- virtual void **applyB0** ([Vector](#)< Real > &Bv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &x)
- void **applyB** ([Vector](#)< Real > &Bv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &x)

Private Attributes

- bool **updateIterate_**

5.11.1 Detailed Description

`template<class Real> class ROL::ISR1< Real >`

Provides definitions for limited-memory SR1 operators.

Definition at line 54 of file ROL_ISR1.hpp.

The documentation for this class was generated from the following file:

- ROL_ISR1.hpp

5.12 ROL::NonlinearCG< Real > Class Template Reference

Implementats nonlinear conjugate gradient methods.

```
#include <ROL_NonlinearCG.hpp>
```

Public Member Functions

- **NonlinearCG** (ENonlinearCG type, int restart=100)
- Teuchos::RCP< [NonlinearCGState](#)< Real > > & **get_state** ()
- virtual void **run** ([Vector](#)< Real > &s, const [Vector](#)< Real > &g, const [Vector](#)< Real > &x, [Objective](#)< Real > &obj)

Private Attributes

- Teuchos::RCP< [NonlinearCGState](#)< Real > > **state_**

5.12.1 Detailed Description

```
template<class Real> class ROL::NonlinearCG< Real >
```

Implementats nonlinear conjugate gradient methods.

Definition at line 65 of file ROL_NonlinearCG.hpp.

The documentation for this class was generated from the following file:

- ROL_NonlinearCG.hpp

5.13 ROL::NonlinearCGState< Real > Struct Template Reference

Public Attributes

- `std::vector< Teuchos::RCP< Vector< Real > > >` **grad**
- `std::vector< Teuchos::RCP< Vector< Real > > >` **pstep**
- `int` **iter**
- `int` **restart**
- `ENonlinearCG` **nlcg_type**

5.13.1 Detailed Description

`template<class Real> struct ROL::NonlinearCGState< Real >`

Definition at line 56 of file ROL_NonlinearCG.hpp.

The documentation for this struct was generated from the following file:

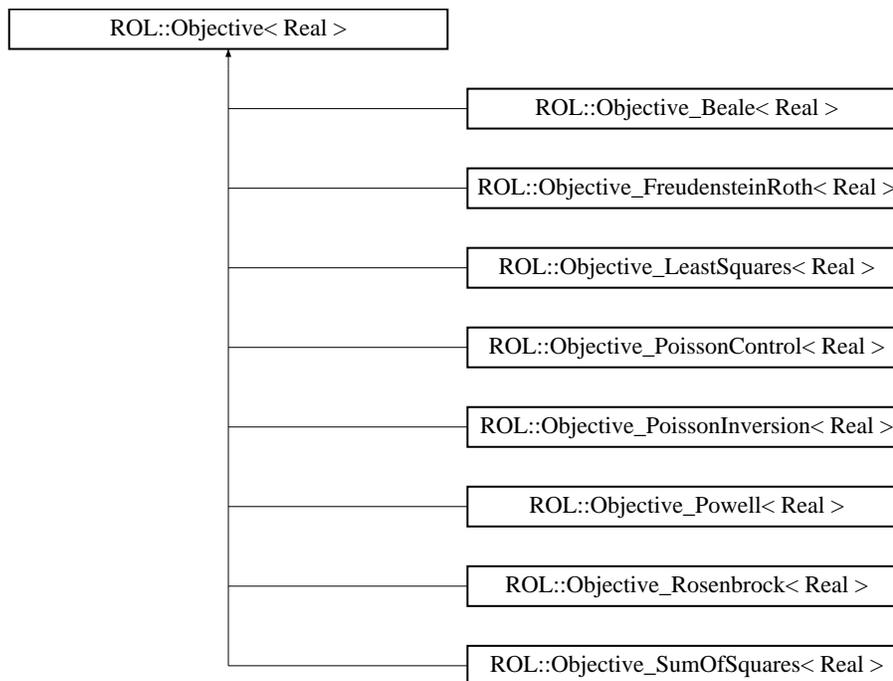
- ROL_NonlinearCG.hpp

5.14 ROL::Objective< Real > Class Template Reference

Provides the interface to evaluate objective functions.

```
#include <ROL_Objective.hpp>
```

Inheritance diagram for ROL::Objective< Real >::



Public Member Functions

- virtual Real [value](#) (const [Vector](#)< Real > &x, Real &tol)=0
Compute value.
- virtual void [gradient](#) ([Vector](#)< Real > &g, const [Vector](#)< Real > &x, Real &tol)
Compute gradient.
- virtual Real [dirDeriv](#) (const [Vector](#)< Real > &x, const [Vector](#)< Real > &d, Real &tol)
Compute directional derivative.

- virtual void `hessVec` (`Vector< Real > &hv`, const `Vector< Real > &v`, const `Vector< Real > &x`, `Real &tol`)
Apply Hessian approximation to vector.
- virtual void `invHessVec` (`Vector< Real > &hv`, const `Vector< Real > &v`, const `Vector< Real > &x`, `Real &tol`)
Apply inverse Hessian approximation to vector.
- virtual void `precond` (`Vector< Real > &Pv`, const `Vector< Real > &v`, const `Vector< Real > &x`)
Apply preconditioner to vector.
- virtual `std::vector< std::vector< Real > >` `checkGradient` (const `Vector< Real > &x`, const `Vector< Real > &d`, const bool `printToScreen=true`, const int `numSteps=ROL_NUM_CHECKDERIV_STEPS`)
Finite-difference gradient check.
- virtual `std::vector< std::vector< Real > >` `checkHessVec` (const `Vector< Real > &x`, const `Vector< Real > &v`, const bool `printToScreen=true`, const int `numSteps=ROL_NUM_CHECKDERIV_STEPS`)
Finite-difference Hessian-applied-to-vector check.

5.14.1 Detailed Description

`template<class Real> class ROL::Objective< Real >`

Provides the interface to evaluate objective functions. Provides the definition of the objective function interface.

Definition at line 59 of file `ROL_Objective.hpp`.

The documentation for this class was generated from the following files:

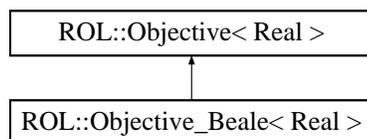
- `ROL_Objective.hpp`
- `ROL_ObjectiveDef.hpp`

5.15 ROL::Objective_Beale< Real > Class Template Reference

Beale's function.

```
#include <ROL_Beale.hpp>
```

Inheritance diagram for ROL::Objective_Beale< Real >::



Public Member Functions

- Real `value` (const `Vector< Real >` &x, Real &tol)
Compute value.
- void `gradient` (`Vector< Real >` &g, const `Vector< Real >` &x, Real &tol)
Compute gradient.
- void `hessVec` (`Vector< Real >` &hv, const `Vector< Real >` &v, const `Vector< Real >` &x, Real &tol)
Apply Hessian approximation to vector.
- void `invHessVec` (`Vector< Real >` &hv, const `Vector< Real >` &v, const `Vector< Real >` &x, Real &tol)
Apply inverse Hessian approximation to vector.

Private Attributes

- `std::vector< Real >` `y_`

5.15.1 Detailed Description

```
template<class Real> class ROL::Objective_Beale< Real >
```

Beale's function.

Definition at line 64 of file ROL_Beale.hpp.

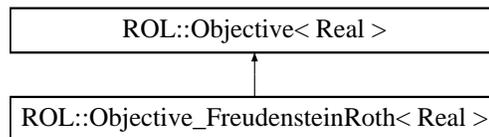
The documentation for this class was generated from the following file:

- [ROL_Beale.hpp](#)

5.16 ROL::Objective_FreudensteinRoth< Real > Class Template Reference

Freudenstein and Roth's function.

`#include <ROL_FreudensteinRoth.hpp>` Inheritance diagram for ROL::Objective_FreudensteinRoth< Real >::



Public Member Functions

- Real `value` (const `Vector< Real >` &x, Real &tol)
Compute value.
- void `gradient` (`Vector< Real >` &g, const `Vector< Real >` &x, Real &tol)
Compute gradient.
- void `hessVec` (`Vector< Real >` &hv, const `Vector< Real >` &v, const `Vector< Real >` &x, Real &tol)
Apply Hessian approximation to vector.
- void `invHessVec` (`Vector< Real >` &hv, const `Vector< Real >` &v, const `Vector< Real >` &x, Real &tol)
Apply inverse Hessian approximation to vector.

5.16.1 Detailed Description

`template<class Real> class ROL::Objective_FreudensteinRoth< Real >`

Freudenstein and Roth's function.

Definition at line 64 of file ROL_FreudensteinRoth.hpp.

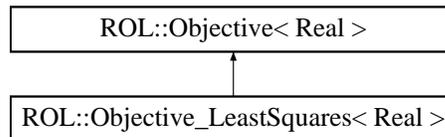
The documentation for this class was generated from the following file:

- [ROL_FreudensteinRoth.hpp](#)

5.17 ROL::Objective_LeastSquares< Real > Class Template Reference

Least squares function.

`#include <ROL_LeastSquares.hpp>` Inheritance diagram for ROL::Objective_LeastSquares< Real >::



Public Member Functions

- Real [value](#) (const [Vector](#)< Real > &x, Real &tol)
Compute value.
- void [gradient](#) ([Vector](#)< Real > &g, const [Vector](#)< Real > &x, Real &tol)
Compute gradient.
- void [hessVec](#) ([Vector](#)< Real > &hv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &x, Real &tol)
Apply Hessian approximation to vector.

5.17.1 Detailed Description

`template<class Real> class ROL::Objective_LeastSquares< Real >`

Least squares function.

Definition at line 64 of file ROL_LeastSquares.hpp.

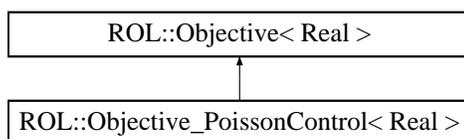
The documentation for this class was generated from the following file:

- [ROL_LeastSquares.hpp](#)

5.18 ROL::Objective_PoissonControl< Real > Class Template Reference

Poisson distributed control.

`#include <ROL_PoissonControl.hpp>` Inheritance diagram for ROL::Objective_PoissonControl< Real >::



Public Member Functions

- **Objective_PoissonControl** (Real alpha=1.e-4)
- void **apply_mass** (Vector< Real > &Mz, const Vector< Real > &z)
- void **solve_poisson** (Vector< Real > &u, const Vector< Real > &z)
- Real **evaluate_target** (Real x)
- Real **value** (const Vector< Real > &z, Real &tol)
Compute value.
- void **gradient** (Vector< Real > &g, const Vector< Real > &z, Real &tol)
Compute gradient.
- void **hessVec** (Vector< Real > &hv, const Vector< Real > &v, const Vector< Real > &z, Real &tol)
Apply Hessian approximation to vector.

Private Attributes

- Real **alpha_**

5.18.1 Detailed Description

`template<class Real> class ROL::Objective_PoissonControl< Real >`

Poisson distributed control.

Definition at line 64 of file ROL_PoissonControl.hpp.

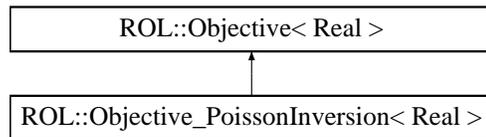
The documentation for this class was generated from the following file:

- [ROL_PoissonControl.hpp](#)

5.19 ROL::Objective_PoissonInversion< Real > Class Template Reference

Poisson material inversion.

`#include <ROL_PoissonInversion.hpp>` Inheritance diagram for ROL::Objective_PoissonInversion< Real >::



Public Member Functions

- **Objective_PoissonInversion** (int nz=32, Real alpha=1.e-4)
- Real **reg_value** (const [Vector](#)< Real > &z)
- void **reg_gradient** ([Vector](#)< Real > &g, const [Vector](#)< Real > &z)
- void **reg_hessVec** ([Vector](#)< Real > &hv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &z)
- void **apply_mass** ([Vector](#)< Real > &Mf, const [Vector](#)< Real > &f)
- void **solve_poisson** ([Vector](#)< Real > &u, const [Vector](#)< Real > &z, [Vector](#)< Real > &b)
- Real **evaluate_target** (Real x)
- void **apply_linearized_control_operator** ([Vector](#)< Real > &Bd, const [Vector](#)< Real > &z, const [Vector](#)< Real > &d, const [Vector](#)< Real > &u)
- void **apply_transposed_linearized_control_operator** ([Vector](#)< Real > &Bd, const [Vector](#)< Real > &z, const [Vector](#)< Real > &d, const [Vector](#)< Real > &u)
- void **apply_transposed_linearized_control_operator_2** ([Vector](#)< Real > &Bd, const [Vector](#)< Real > &z, const [Vector](#)< Real > &v, const [Vector](#)< Real > &d, const [Vector](#)< Real > &u)
- void **solve_state_equation** ([Vector](#)< Real > &u, const [Vector](#)< Real > &z)
- void **solve_adjoint_equation** ([Vector](#)< Real > &p, const [Vector](#)< Real > &u, const [Vector](#)< Real > &z)
- void **solve_state_sensitivity_equation** ([Vector](#)< Real > &w, const [Vector](#)< Real > &v, const [Vector](#)< Real > &u, const [Vector](#)< Real > &z)
- void **solve_adjoint_sensitivity_equation** ([Vector](#)< Real > &q, const [Vector](#)< Real > &w, const [Vector](#)< Real > &v, const [Vector](#)< Real > &p, const [Vector](#)< Real > &u, const [Vector](#)< Real > &z)
- Real **value** (const [Vector](#)< Real > &z, Real &tol)

Compute value.

- void `gradient` (`Vector< Real >` &g, const `Vector< Real >` &z, Real &tol)
Compute gradient.
- void `hessVec` (`Vector< Real >` &hv, const `Vector< Real >` &v, const `Vector< Real >` &z, Real &tol)
Apply Hessian approximation to vector.

Private Attributes

- int `nu_`
- int `nz_`
- Real `hu_`
- Real `hz_`
- Real `alpha_`
- Real `eps_`
- int `reg_type_`

5.19.1 Detailed Description

`template<class Real> class ROL::Objective_PoissonInversion< Real >`

Poisson material inversion.

Definition at line 66 of file `ROL_PoissonInversion.hpp`.

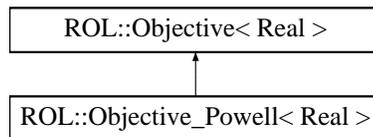
The documentation for this class was generated from the following file:

- [ROL_PoissonInversion.hpp](#)

5.20 ROL::Objective_Powell< Real > Class Template Reference

Powell's badly scaled function.

#include <ROL_Powell.hpp> Inheritance diagram for ROL::Objective_Powell< Real >::



Public Member Functions

- Real [value](#) (const [Vector](#)< Real > &x, Real &tol)
Compute value.
- void [gradient](#) ([Vector](#)< Real > &g, const [Vector](#)< Real > &x, Real &tol)
Compute gradient.
- void [hessVec](#) ([Vector](#)< Real > &hv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &x, Real &tol)
Apply Hessian approximation to vector.
- void [invHessVec](#) ([Vector](#)< Real > &hv, const [Vector](#)< Real > &v, const [Vector](#)< Real > &x, Real &tol)
Apply inverse Hessian approximation to vector.

5.20.1 Detailed Description

template<class Real> class ROL::Objective_Powell< Real >

Powell's badly scaled function.

Definition at line 64 of file ROL_Powell.hpp.

The documentation for this class was generated from the following file:

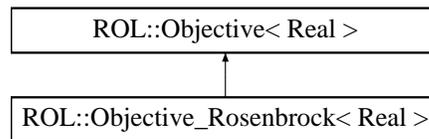
- [ROL_Powell.hpp](#)

5.21 ROL::Objective_Rosenbrock< Real > Class Template Reference

Rosenbrock's function.

```
#include <ROL_Rosenbrock.hpp>
```

Inheritance diagram for ROL::Objective_Rosenbrock< Real >::



Public Member Functions

- **Objective_Rosenbrock** (Real alpha=100.0)
- Real **value** (const **Vector**< Real > &x, Real &tol)
Compute value.
- void **gradient** (**Vector**< Real > &g, const **Vector**< Real > &x, Real &tol)
Compute gradient.
- void **hessVec** (**Vector**< Real > &hv, const **Vector**< Real > &v, const **Vector**< Real > &x, Real &tol)
Apply Hessian approximation to vector.
- void **invHessVec** (**Vector**< Real > &hv, const **Vector**< Real > &v, const **Vector**< Real > &x, Real &tol)
Apply inverse Hessian approximation to vector.

Private Attributes

- Real **alpha_**

5.21.1 Detailed Description

```
template<class Real> class ROL::Objective_Rosenbrock< Real >
```

Rosenbrock's function.

Definition at line 64 of file ROL_Rosenbrock.hpp.

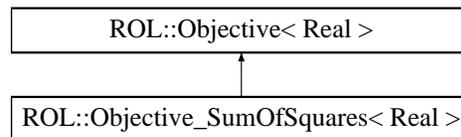
The documentation for this class was generated from the following file:

- [ROL_Rosenbrock.hpp](#)

5.22 ROL::Objective_SumOfSquares< Real > Class Template Reference

Sum of squares function.

`#include <ROL_SumOfSquares.hpp>` **Inheritance** diagram for `ROL::Objective_SumOfSquares< Real >::`



Public Member Functions

- `Real value` (`const Vector< Real > &x, Real &tol`)
Compute value.
- `void gradient` (`Vector< Real > &g, const Vector< Real > &x, Real &tol`)
Compute gradient.
- `void hessVec` (`Vector< Real > &hv, const Vector< Real > &v, const Vector< Real > &x, Real &tol`)
Apply Hessian approximation to vector.
- `void invHessVec` (`Vector< Real > &hv, const Vector< Real > &v, const Vector< Real > &x, Real &tol`)
Apply inverse Hessian approximation to vector.

5.22.1 Detailed Description

`template<class Real> class ROL::Objective_SumOfSquares< Real >`

Sum of squares function.

Definition at line 64 of file `ROL_SumOfSquares.hpp`.

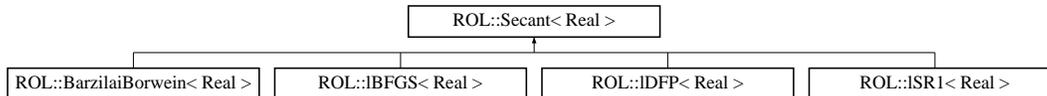
The documentation for this class was generated from the following file:

- [ROL_SumOfSquares.hpp](#)

5.23 ROL::Secant< Real > Class Template Reference

Provides interface for and implements limited-memory secant operators.

`#include <ROL_Secant.hpp>` Inheritance diagram for ROL::Secant< Real >::



Public Member Functions

- **Secant** (int M=10)
- Teuchos::RCP< SecantState< Real > > & **get_state** ()
- virtual void **update** (const Vector< Real > &grad, const Vector< Real > &gp, const Vector< Real > &s, const Real snorm, const int iter)
- virtual void **applyH** (Vector< Real > &Hv, const Vector< Real > &v, const Vector< Real > &x)=0
- virtual void **applyH0** (Vector< Real > &Hv, const Vector< Real > &v, const Vector< Real > &x)
- virtual void **applyB** (Vector< Real > &Bv, const Vector< Real > &v, const Vector< Real > &x)=0
- virtual void **applyB0** (Vector< Real > &Bv, const Vector< Real > &v, const Vector< Real > &x)
- void **test** (const Vector< Real > &x, const Vector< Real > &s)

Private Attributes

- Teuchos::RCP< SecantState< Real > > **state_**

5.23.1 Detailed Description

`template<class Real> class ROL::Secant< Real >`

Provides interface for and implements limited-memory secant operators.

Definition at line 67 of file ROL_Secant.hpp.

The documentation for this class was generated from the following file:

- ROL_Secant.hpp

5.24 ROL::SecantState< Real > Struct Template Reference

Public Attributes

- `std::vector< Teuchos::RCP< Vector< Real > > > iterDiff`
- `std::vector< Teuchos::RCP< Vector< Real > > > gradDiff`
- `std::vector< Real > product`
- `std::vector< Real > product2`
- `int storage`
- `int current`
- `int iter`

5.24.1 Detailed Description

`template<class Real> struct ROL::SecantState< Real >`

Definition at line 56 of file ROL_Secant.hpp.

The documentation for this struct was generated from the following file:

- ROL_Secant.hpp

5.25 ROL::StatusTest< Real > Class Template Reference

Provides an interface to check status of optimization algorithms.

```
#include <ROL_StatusTest.hpp>
```

Public Member Functions

- **StatusTest** (Real gtol=1.e-6, Real stol=1.e-12, int max_iter=100)
- virtual bool **check** ([AlgorithmState](#)< Real > &state)

Check algorithm status.

Private Attributes

- Real **gtol_**
- Real **stol_**
- int **max_iter_**

5.25.1 Detailed Description

```
template<class Real> class ROL::StatusTest< Real >
```

Provides an interface to check status of optimization algorithms.

Definition at line 56 of file ROL_StatusTest.hpp.

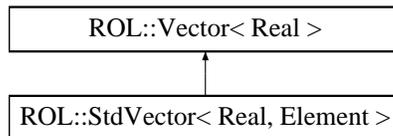
The documentation for this class was generated from the following file:

- ROL_StatusTest.hpp

5.26 ROL::StdVector< Real, Element > Class Template Reference

Provides the `std::vector` implementation of the [ROL::Vector](#) interface.

`#include <ROL_StdVector.hpp>` Inheritance diagram for `ROL::StdVector< Real, Element >::`



Public Member Functions

- **StdVector** (const Teuchos::RCP< std::vector< Element > > &std_vec)
- void **plus** (const [Vector](#)< Real > &x)
- void **scale** (const Real alpha)

*Compute $y \leftarrow \alpha y$ where $y = *this$.*
- Real **dot** (const [Vector](#)< Real > &x) const
- Real **norm** () const

*Returns $\|y\|$ where $y = *this$.*
- Teuchos::RCP< [Vector](#)< Real > > **clone** () const

Clone to make a new (uninitialized) vector.
- Teuchos::RCP< const std::vector< Element > > **getVector** () const
- Teuchos::RCP< [Vector](#)< Real > > **basis** (const int i) const

Return i -th basis vector: define if finite-difference gradients and Hessians are used.
- int **dimension** ()

Return dimension of the vector space.

Private Attributes

- Teuchos::RCP< std::vector< Element > > **std_vec_**

5.26.1 Detailed Description

```
template<class Real, class Element = Real> class ROL::StdVector< Real, Element >
```

Provides the std::vector implementation of the [ROL::Vector](#) interface.

Definition at line 57 of file ROL_StdVector.hpp.

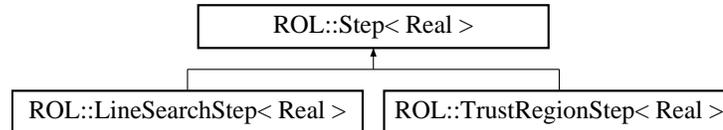
The documentation for this class was generated from the following file:

- ROL_StdVector.hpp

5.27 ROL::Step< Real > Class Template Reference

Provides the interface to compute optimization steps.

#include <ROL_Step.hpp> Inheritance diagram for ROL::Step< Real >::



Public Member Functions

- Teuchos::RCP< StepState< Real > > & **get_state** ()
- virtual void **initialize** (const Vector< Real > &x, Objective< Real > &obj, AlgorithmState< Real > &algo_state)

Initialize step.

- virtual void **compute** (Vector< Real > &s, const Vector< Real > &x, Objective< Real > &obj, AlgorithmState< Real > &algo_state)=0

Compute step.

- virtual void **update** (Vector< Real > &x, const Vector< Real > &s, Objective< Real > &obj, AlgorithmState< Real > &algo_state)=0

Update step, if successful.

- virtual std::string **printHeader** (void) const =0

Print iterate header.

- virtual std::string **printName** (void) const =0

Print step name.

- virtual std::string **print** (AlgorithmState< Real > &algo_state, bool printHeader=false) const =0

Print iterate status.

Public Attributes

- Teuchos::RCP< StepState< Real > > **state_**

5.27.1 Detailed Description

template<class Real> class ROL::Step< Real >

Provides the interface to compute optimization steps.

Definition at line 76 of file ROL_Step.hpp.

The documentation for this class was generated from the following file:

- ROL_Step.hpp

5.28 ROL::StepState< Real > Struct Template Reference

Public Attributes

- Teuchos::RCP< [Vector](#)< Real > > **gradientVec**
- Teuchos::RCP< [Vector](#)< Real > > **descentVec**

5.28.1 Detailed Description

template<class Real> struct ROL::StepState< Real >

Definition at line 69 of file ROL_Step.hpp.

The documentation for this struct was generated from the following file:

- ROL_Step.hpp

5.29 ROL::TrustRegion< Real > Class Template Reference

Provides interface for and implements trust-region subproblem solvers.

```
#include <ROL_TrustRegion.hpp>
```

Public Member Functions

- **TrustRegion** (Teuchos::ParameterList &parlist)
- void **update** ([Vector](#)< Real > &x, Real &fnw, Real &del, int &nfval, int &ngrad, int &flagTR, const [Vector](#)< Real > &s, const Real snorm, const Real fold, const [Vector](#)< Real > &g, [Objective](#)< Real > &obj, Teuchos::RCP< [Secant](#)< Real > > &secant=Teuchos::null)
- void **run** ([Vector](#)< Real > &s, Real &snorm, Real &del, int &iflag, int &iter, const [Vector](#)< Real > &x, const [Vector](#)< Real > &grad, const Real &gnorm, [Objective](#)< Real > &obj, Teuchos::RCP< [Secant](#)< Real > > &secant=Teuchos::null)
- void **cauchy** ([Vector](#)< Real > &s, Real &snorm, Real &del, int &iflag, int &iter, const [Vector](#)< Real > &x, const [Vector](#)< Real > &grad, const Real &gnorm, [Objective](#)< Real > &obj, Teuchos::RCP< [Secant](#)< Real > > &secant=Teuchos::null)
- void **truncatedCG** ([Vector](#)< Real > &s, Real &snorm, Real &del, int &iflag, int &iter, const [Vector](#)< Real > &x, const [Vector](#)< Real > &grad, const Real &gnorm, [Objective](#)< Real > &obj, Teuchos::RCP< [Secant](#)< Real > > &secant=Teuchos::null)
- void **dogleg** ([Vector](#)< Real > &s, Real &snorm, Real &del, int &iflag, int &iter, const [Vector](#)< Real > &x, const [Vector](#)< Real > &grad, const Real &gnorm, [Objective](#)< Real > &obj, Teuchos::RCP< [Secant](#)< Real > > &secant=Teuchos::null)
- void **doubledogleg** ([Vector](#)< Real > &s, Real &snorm, Real &del, int &iflag, int &iter, const [Vector](#)< Real > &x, const [Vector](#)< Real > &grad, const Real &gnorm, [Objective](#)< Real > &obj, Teuchos::RCP< [Secant](#)< Real > > &secant=Teuchos::null)

Private Attributes

- ETrustRegion **etr_**
- bool **useSecantPrecond_**
- bool **useSecantHessVec_**
- int **maxit_**
- Real **tol1_**
- Real **tol2_**

- Real **delmin**_
- Real **delmax**_
- Real **eta0**_
- Real **eta1**_
- Real **eta2**_
- Real **gamma0**_
- Real **gamma1**_
- Real **gamma2**_
- Real **pRed**_
- Real **TRsafe**_
- Real **eps**_

5.29.1 Detailed Description

`template<class Real> class ROL::TrustRegion< Real >`

Provides interface for and implements trust-region subproblem solvers.

Definition at line 56 of file ROL_TrustRegion.hpp.

The documentation for this class was generated from the following file:

- ROL_TrustRegion.hpp

5.30 ROL::TrustRegionStep< Real > Class Template Reference

Provides the interface to compute optimization steps with trust regions.

#include <ROL_TrustRegionStep.hpp> **Inheritance diagram** for ROL::TrustRegionStep< Real >::



Public Member Functions

- **TrustRegionStep** (Teuchos::ParameterList &parlist)
- **TrustRegionStep** (Teuchos::RCP< [Secant](#)< Real > > &secant, Teuchos::ParameterList &parlist)
- void **initialize** (const [Vector](#)< Real > &x, [Objective](#)< Real > &obj, [AlgorithmState](#)< Real > &algo_state)
Initialize step.
- void **compute** ([Vector](#)< Real > &s, const [Vector](#)< Real > &x, [Objective](#)< Real > &obj, [AlgorithmState](#)< Real > &algo_state)
Compute step.
- void **update** ([Vector](#)< Real > &x, const [Vector](#)< Real > &s, [Objective](#)< Real > &obj, [AlgorithmState](#)< Real > &algo_state)
Update step, if successful.
- std::string **printHeader** (void) const
Print iterate header.
- std::string **printName** (void) const
Print step name.
- std::string **print** ([AlgorithmState](#)< Real > &algo_state, bool printHeader=false) const
Print iterate status.

Private Attributes

- Teuchos::RCP< [Secant](#)< Real > > **secant_**
- Teuchos::RCP< [TrustRegion](#)< Real > > **trustRegion_**
- ETrustRegion **etr_**
- ESecant **esec_**
- bool **useSecantHessVec_**
- bool **useSecantPrecond_**
- Real **del_**
- std::vector< bool > **useInexact_**
- int **TRflag_**
- int **TR_nfval_**
- int **TR_ngrad_**
- int **CGflag_**
- int **CGiter_**

5.30.1 Detailed Description

`template<class Real> class ROL::TrustRegionStep< Real >`

Provides the interface to compute optimization steps with trust regions.

Definition at line 63 of file `ROL_TrustRegionStep.hpp`.

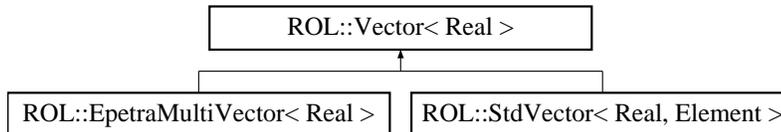
The documentation for this class was generated from the following file:

- `ROL_TrustRegionStep.hpp`

5.31 ROL::Vector< Real > Class Template Reference

Provides the vector space interface.

`#include <ROL_Vector.hpp>` Inheritance diagram for ROL::Vector< Real >::



Public Member Functions

- virtual void **plus** (const **Vector** &x)=0
*Compute $y \leftarrow x + y$ where $y = *this$.*
- virtual void **scale** (const Real alpha)=0
*Compute $y \leftarrow \alpha y$ where $y = *this$.*
- virtual Real **dot** (const **Vector** &x) const =0
*Returns $\langle y, x \rangle$ where $y = *this$.*
- virtual Real **norm** () const =0
*Returns $\|y\|$ where $y = *this$.*
- virtual Teuchos::RCP< **Vector** > **clone** () const =0
Clone to make a new (uninitialized) vector.
- virtual void **axpy** (const Real alpha, const **Vector** &x)
*Compute $y \leftarrow \alpha x + y$ where $y = *this$.*
- virtual void **zero** ()
Set to zero vector.
- virtual Teuchos::RCP< **Vector** > **basis** (const int i) const
Return i -th basis vector: define if finite-difference gradients and Hessians are used.
- virtual int **dimension** ()
Return dimension of the vector space.
- virtual void **set** (const **Vector** &x)
*Set $y \leftarrow x$ where $y = *this$.*

5.31.1 Detailed Description

template<class Real> class ROL::Vector< Real >

Provides the vector space interface. The basic interface to be supplied by the user includes:

- vector addition,
- scalar multiplication,
- dot (scalar) product of vectors,
- vector norm,
- cloning of vectors.

The dot product can represent an inner product (in Hilbert space) or a duality pairing (in general Banach space).

There are additional virtual member functions that the user may want to reimplement for added efficiency.

Definition at line 70 of file ROL_Vector.hpp.

The documentation for this class was generated from the following file:

- ROL_Vector.hpp

Chapter 6

File Documentation

6.1 example_01.cpp File Reference

Shows how to minimize Rosenbrock's function using Newton-Krylov. #include "ROL_Rosenbrock.hpp"
#include "ROL_LineSearchStep.hpp"
#include "ROL_Algorithm.hpp"
#include "Teuchos_oblackholestream.hpp"
#include "Teuchos_GlobalMPISession.hpp"
#include <iostream>

Defines

- #define USE_HESSVEC 1

Typedefs

- typedef double **RealT**

Functions

- int **main** (int argc, char *argv[])

6.1.1 Detailed Description

Shows how to minimize Rosenbrock's function using Newton-Krylov.

Definition in file [example_01.cpp](#).

6.2 ROL_Beale.hpp File Reference

Contains definitions for Beale's function. `#include "ROL_StdVector.hpp"`
`#include "ROL_Objective.hpp"`

Classes

- class [ROL::Objective_Beale< Real >](#)
Beale's function.

Defines

- `#define USE_HESSVEC 1`

Functions

- `template<class Real >`
`void ROL::getBeale (Teuchos::RCP< Objective< Real > > &obj, Vector<`
`Real > &x0, Vector< Real > &x)`

6.2.1 Detailed Description

Contains definitions for Beale's function.

Author:

Created by D. Ridzal and D. Kouri.

Definition in file [ROL_Beale.hpp](#).

6.3 ROL_FreudensteinRoth.hpp File Reference

Contains definitions for Freudenstein and Roth's function. `#include "ROL_StdVector.hpp"`

`#include "ROL_Objective.hpp"`

Classes

- class [ROL::Objective_FreudensteinRoth< Real >](#)
Freudenstein and Roth's function.

Functions

- `template<class Real >`
`void ROL::getFreudensteinRoth (Teuchos::RCP< Objective< Real > >`
`&obj, Vector< Real > &x0, Vector< Real > &x)`

6.3.1 Detailed Description

Contains definitions for Freudenstein and Roth's function.

Author:

Created by D. Ridzal and D. Kouri.

Definition in file [ROL_FreudensteinRoth.hpp](#).

6.4 ROL_LeastSquares.hpp File Reference

Contains definitions for least squares function. #include "ROL_StdVector.hpp"

include "ROL_Objective.hpp"

Classes

- class [ROL::Objective_LeastSquares< Real >](#)
Least squares function.

Functions

- template<class Real >
void **ROL::getLeastSquares** (Teuchos::RCP< Objective< Real > > &obj,
Vector< Real > &x0, Vector< Real > &x)

6.4.1 Detailed Description

Contains definitions for least squares function.

Author:

Created by D. Ridzal and D. Kouri.

Definition in file [ROL_LeastSquares.hpp](#).

6.5 ROL_PoissonControl.hpp File Reference

Contains definitions for Poisson optimal control. `#include "ROL_StdVector.hpp"`

`#include "ROL_Objective.hpp"`

Classes

- class [ROL::Objective_PoissonControl< Real >](#)
Poisson distributed control.

Functions

- `template<class Real >`
void **ROL::getPoissonControl** (Teuchos::RCP< Objective< Real > > &obj,
Vector< Real > &x0, Vector< Real > &x)

6.5.1 Detailed Description

Contains definitions for Poisson optimal control.

Author:

Created by D. Ridzal and D. Kouri.

Definition in file [ROL_PoissonControl.hpp](#).

6.6 ROL_PoissonInversion.hpp File Reference

Contains definitions for Poisson material inversion. `#include "ROL_StdVector.hpp"`

`#include "ROL_Objective.hpp"`

`#include "Teuchos_LAPACK.hpp"`

Classes

- class [ROL::Objective_PoissonInversion< Real >](#)
Poisson material inversion.

Functions

- `template<class Real >`
void **ROL::getPoissonInversion** (Teuchos::RCP< Objective< Real > > &obj,
Vector< Real > &x0, Vector< Real > &x)

6.6.1 Detailed Description

Contains definitions for Poisson material inversion.

Author:

Created by D. Ridzal and D. Kouri.

Definition in file [ROL_PoissonInversion.hpp](#).

6.7 ROL_Powell.hpp File Reference

Contains definitions for Powell's badly scaled function. `#include "ROL_StdVector.hpp"`

`#include "ROL_Objective.hpp"`

Classes

- class [ROL::Objective_Powell< Real >](#)
Powell's badly scaled function.

Functions

- `template<class Real >`
`void ROL::getPowell (Teuchos::RCP< Objective< Real > > &obj, Vector< Real > &x0, Vector< Real > &x)`

6.7.1 Detailed Description

Contains definitions for Powell's badly scaled function.

Author:

Created by D. Ridzal and D. Kouri.

Definition in file [ROL_Powell.hpp](#).

6.8 ROL_Rosenbrock.hpp File Reference

Contains definitions for Rosenbrock's function. `#include "ROL_StdVector.hpp"`
`#include "ROL_Objective.hpp"`

Classes

- class [ROL::Objective_Rosenbrock< Real >](#)
Rosenbrock's function.

Functions

- `template<class Real >`
void **ROL::getRosenbrock** (Teuchos::RCP< Objective< Real > > &obj,
Vector< Real > &x0, Vector< Real > &x)

6.8.1 Detailed Description

Contains definitions for Rosenbrock's function.

Author:

Created by D. Ridzal and D. Kouri.

Definition in file [ROL_Rosenbrock.hpp](#).

6.9 ROL_SumOfSquares.hpp File Reference

Contains definitions for sum of squares function. `#include "ROL_StdVector.hpp"`

`#include "ROL_Objective.hpp"`

Classes

- class [ROL::Objective_SumOfSquares< Real >](#)
Sum of squares function.

Functions

- `template<class Real >`
`void ROL::getSumOfSquares (Teuchos::RCP< Objective< Real > > &obj,`
`Vector< Real > &x0, Vector< Real > &x)`

6.9.1 Detailed Description

Contains definitions for sum of squares function.

Author:

Created by D. Ridzal and D. Kouri.

Definition in file [ROL_SumOfSquares.hpp](#).

6.10 ROL_TestObjectives.hpp File Reference

Contains definitions of test objective functions. #include "ROL_
Rosenbrock.hpp"
#include "ROL_FreudensteinRoth.hpp"
#include "ROL_Beale.hpp"
#include "ROL_Powell.hpp"
#include "ROL_SumOfSquares.hpp"
#include "ROL_LeastSquares.hpp"
#include "ROL_PoissonControl.hpp"
#include "ROL_PoissonInversion.hpp"
#include "ROL_Types.hpp"
#include "ROL_StdVector.hpp"
#include "ROL_Objective.hpp"

Functions

- template<class Real >
void **ROL::getTestObjectives** (Teuchos::RCP< Objective< Real > > &obj,
Vector< Real > &x0, Vector< Real > &x, const ETestObjectives test)

6.10.1 Detailed Description

Contains definitions of test objective functions.

Author:

Created by D. Ridzal and D. Kouri.

Definition in file [ROL_TestObjectives.hpp](#).

6.11 ROL_Types.hpp File Reference

Contains definitions of custom data types in ROL. `#include <Teuchos_ScalarTraits.hpp>`

`#include <Teuchos_TestForException.hpp>`

Defines

- `#define ROL_VALIDATE(A)`
- `#define ROL_NUM_CHECKDERIV_STEPS 13`
Number of steps for derivative checks.

Enumerations

- enum **EDescent** {
DESCENT_STEEPEST = 0, DESCENT_NONLINEARCG, DESCENT_SECANT, DESCENT_NEWTON,
DESCENT_NEWTONKRYLOV, DESCENT_SECANTPRECOND,
DESCENT_LAST }
Enumeration of descent direction types.
- enum **ESecant** {
SECANT_LBFGS = 0, SECANT_LDFP, SECANT_LSR1, SECANT_BARZILAIBORWEIN,
SECANT_USERDEFINED, SECANT_LAST }
Enumeration of secant update algorithms.
- enum **ENonlinearCG** {
NONLINEARCG_HESTENES_STIEFEL = 0, NONLINEARCG_FLETCHER_REEVES, NONLINEARCG_DANIEL, NONLINEARCG_POLAK_RIBIERE,
NONLINEARCG_FLETCHER_CONJDESC, NONLINEARCG_LIU_STOREY, NONLINEARCG_DAI_YUAN, NONLINEARCG_HAGAR_ZHANG,
NONLINEARCG_LAST }
Enumeration of nonlinear CG algorithms.

- enum **ELineSearch** {
LINESEARCH_BACKTRACKING = 0, **LINESEARCH_BISECTION**,
LINESEARCH_GOLDENSECTION, **LINESEARCH_CUBICINTERP**,
LINESEARCH_BRENTP, **LINESEARCH_LAST** }
Enumeration of line-search types.
- enum **ECurvatureCondition** { **CURVATURECONDITION_-**
WOLFE = 0, **CURVATURECONDITION_STRONGWOLFE**,
CURVATURECONDITION_GOLDSTEIN, **CURVATURECONDITION_-**
LAST }
Enumeration of line-search curvature conditions.
- enum **ETrustRegion** {
TRUSTREGION_CAUCHYPOINT = 0, **TRUSTREGION_-**
TRUNCATEDCG, **TRUSTREGION_DOGLEG**, **TRUSTREGION_-**
DOUBLEDLEG,
TRUSTREGION_LAST }
Enumeration of trust-region solver types.
- enum **ETestObjectives** {
TESTOBJECTIVES_ROSENBROCK = 0, **TESTOBJECTIVES_-**
FREUDENSTEINANDROTH, **TESTOBJECTIVES_BEALE**,
TESTOBJECTIVES_POWELL,
TESTOBJECTIVES_SUMOFSQUARES, **TESTOBJECTIVES_-**
LEASTSQUARES, **TESTOBJECTIVES_POISSONCONTROL**,
TESTOBJECTIVES_POISSONINVERSION,
TESTOBJECTIVES_LAST }
Enumeration of test objective functions.

Functions

- std::string **ROL::EDescentToString** (EDescent tr)
- int **ROL::IsValidDescent** (EDescent d)
Verifies validity of a [Secant](#) enum.
- EDescent & **ROL::operator++** (EDescent &type)
- EDescent **ROL::operator++** (EDescent &type, int)
- EDescent & **ROL::operator--** (EDescent &type)
- EDescent **ROL::operator--** (EDescent &type, int)
- std::string **ROL::ESecantToString** (ESecant tr)

- int [ROL::isValidSecant](#) (ESecant s)
Verifies validity of a Secant enum.
- ESecant & **ROL::operator++** (ESecant &type)
- ESecant **ROL::operator++** (ESecant &type, int)
- ESecant & **ROL::operator--** (ESecant &type)
- ESecant **ROL::operator--** (ESecant &type, int)
- std::string **ROL::ENonlinearCGToString** (ENonlinearCG tr)
- int [ROL::isValidNonlinearCG](#) (ENonlinearCG s)
Verifies validity of a NonlinearCG enum.
- ENonlinearCG & **ROL::operator++** (ENonlinearCG &type)
- ENonlinearCG **ROL::operator++** (ENonlinearCG &type, int)
- ENonlinearCG & **ROL::operator--** (ENonlinearCG &type)
- ENonlinearCG **ROL::operator--** (ENonlinearCG &type, int)
- std::string **ROL::ELineSearchToString** (ELineSearch ls)
- int [ROL::isValidLineSearch](#) (ELineSearch ls)
Verifies validity of a LineSearch enum.
- ELineSearch & **ROL::operator++** (ELineSearch &type)
- ELineSearch **ROL::operator++** (ELineSearch &type, int)
- ELineSearch & **ROL::operator--** (ELineSearch &type)
- ELineSearch **ROL::operator--** (ELineSearch &type, int)
- std::string **ROL::ECurvatureConditionToString** (ECurvatureCondition ls)
- int [ROL::isValidCurvatureCondition](#) (ECurvatureCondition ls)
Verifies validity of a CurvatureCondition enum.
- ECurvatureCondition & **ROL::operator++** (ECurvatureCondition &type)
- ECurvatureCondition **ROL::operator++** (ECurvatureCondition &type, int)
- ECurvatureCondition & **ROL::operator--** (ECurvatureCondition &type)
- ECurvatureCondition **ROL::operator--** (ECurvatureCondition &type, int)
- std::string **ROL::ETrustRegionToString** (ETrustRegion tr)
- int [ROL::isValidTrustRegion](#) (ETrustRegion ls)
Verifies validity of a TrustRegion enum.
- ETrustRegion & **ROL::operator++** (ETrustRegion &type)
- ETrustRegion **ROL::operator++** (ETrustRegion &type, int)
- ETrustRegion & **ROL::operator--** (ETrustRegion &type)
- ETrustRegion **ROL::operator--** (ETrustRegion &type, int)
- std::string **ROL::ETestObjectivesToString** (ETestObjectives to)
- int [ROL::isValidTestObjectives](#) (ETestObjectives to)
Verifies validity of a TestObjectives enum.

- ETestObjectives & **ROL::operator++** (ETestObjectives &type)
- ETestObjectives **ROL::operator++** (ETestObjectives &type, int)
- ETestObjectives & **ROL::operator--** (ETestObjectives &type)
- ETestObjectives **ROL::operator--** (ETestObjectives &type, int)

Variables

- static const double **ROL::ROL_EPSILON** =
std::abs(Teuchos::ScalarTraits<double>::eps())
Platform-dependent machine epsilon.
- static const double **ROL::ROL_THRESHOLD** = 10.0 * ROL_EPSILON
Tolerance for various equality tests.

6.11.1 Detailed Description

Contains definitions of custom data types in ROL.

Author:

Created by D. Ridzal and D. Kouri.

Definition in file [ROL_Types.hpp](#).

Index

example_01.cpp, [55](#)

ROL::Algorithm, [11](#)
ROL::AlgorithmState, [12](#)
ROL::BarzilaiBorwein, [13](#)
ROL::DefaultAlgorithm, [14](#)
ROL::EpetraMultiVector, [15](#)
ROL::Krylov, [17](#)
ROL::IBFGS, [18](#)
ROL::IDFP, [19](#)
ROL::LineSearch, [20](#)
ROL::LineSearchStep, [22](#)
ROL::ISR1, [24](#)
ROL::NonlinearCG, [25](#)
ROL::NonlinearCGState, [26](#)
ROL::Objective, [27](#)
ROL::Objective_Beale, [29](#)
ROL::Objective_FreudensteinRoth, [31](#)
ROL::Objective_LeastSquares, [32](#)
ROL::Objective_PoissonControl, [33](#)
ROL::Objective_PoissonInversion, [35](#)
ROL::Objective_Powell, [37](#)
ROL::Objective_Rosenbrock, [38](#)
ROL::Objective_SumOfSquares, [40](#)
ROL::Secant, [41](#)
ROL::SecantState, [42](#)
ROL::StatusTest, [43](#)
ROL::StdVector, [44](#)
ROL::Step, [46](#)
ROL::StepState, [48](#)
ROL::TrustRegion, [49](#)
ROL::TrustRegionStep, [51](#)
ROL::Vector, [53](#)
ROL_Beale.hpp, [57](#)
ROL_FreudensteinRoth.hpp, [58](#)
ROL_LeastSquares.hpp, [59](#)
ROL_PoissonControl.hpp, [60](#)
ROL_PoissonInversion.hpp, [61](#)
ROL_Powell.hpp, [62](#)
ROL_Rosenbrock.hpp, [63](#)
ROL_SumOfSquares.hpp, [64](#)
ROL_TestObjectives.hpp, [65](#)
ROL_Types.hpp, [66](#)